

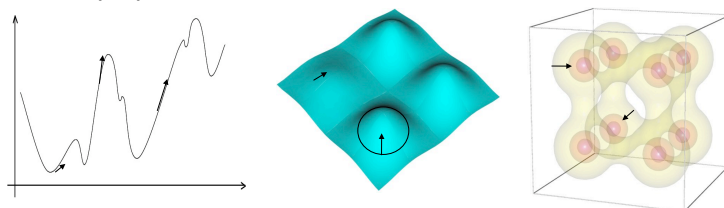
All About Morse-Smale Complexes

What is a Morse-Smale Complex?
 Simplification: cancellations in the complex.
 An algorithm to compute for 2D PL data.
 A discrete algorithm for 3D+ data.



Gradient Vectors

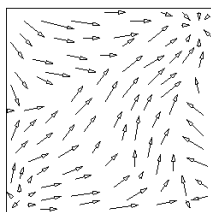
- The gradient of a differentiable scalar function f at a point p is $\nabla f(p) = (\frac{\partial f}{\partial x_0}(p), \dots, \frac{\partial f}{\partial x_n}(p))$
- Direction of steepest ascent
 - perpendicular to contours



Gradient Vector Field

- The vector field given by the gradient vectors of a scalar function is the *gradient vector field*

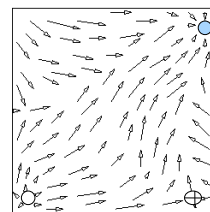
$$\nabla f = (\frac{\partial f}{\partial x_0}, \dots, \frac{\partial f}{\partial x_n})$$



Critical points in GVF

- Critical points where gradient vanishes

$$\nabla f(p) = \mathbf{0}$$



Critical points in GVF - 1D

- Critical points where gradient vanishes

$$\nabla f(p) = \mathbf{0}$$

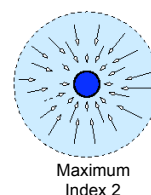
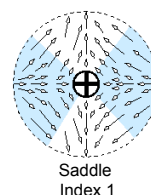


Critical points on a 1d domain

Critical points in GVF - 2D

- Critical points where gradient vanishes

$$\nabla f(p) = \mathbf{0}$$

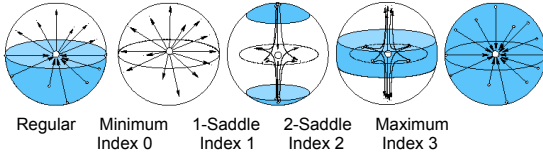


Critical points on a 2d domain

Critical points in GVF - 3D

- Critical points where gradient vanishes

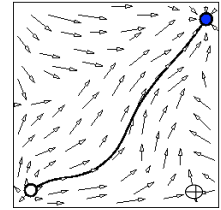
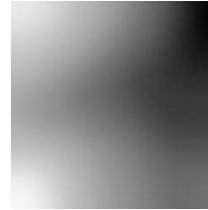
$$\nabla f(p) = \mathbf{0}$$



Critical points on a 3d domain

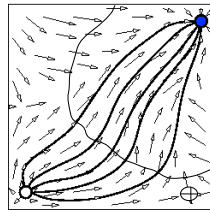
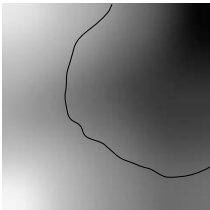
Integral Lines

- Integral Lines
 - Agrees with the gradient at every point on line
 - Has an *origin* and *destination* (lower and upper limits) that are critical points
 - These form boundaries where gradient is zero



Properties of Integral Lines

- Integral Lines
 - DO NOT CROSS
 - Are perpendicular to contours everywhere
 - Cover all non-critical points in entire domain



Ascending/Descending Manifolds

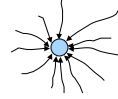
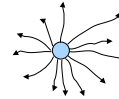
- Ascending/Descending Manifolds
 - Associated with a critical point p

Ascending / unstable

Descending / stable

The collection of points in integral lines where p is the origin

The collection of points in integral lines where p is the destination



Ascending manifolds of f are descending manifolds of $-f$

Ascending manifolds form a cell complex

- boundary of ascending manifolds are lower dim asc manifolds

- two ascending manifolds do not intersect

- ascending manifolds partition M

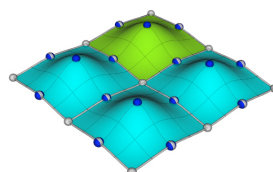
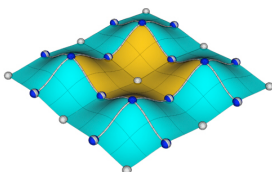
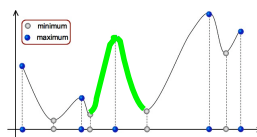
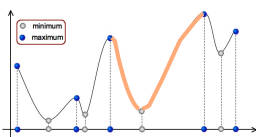
Descending manifolds form a dual cell complex

Ascending/Descending Manifolds

- Ascending/Descending Manifolds

Ascending / unstable

Descending / stable

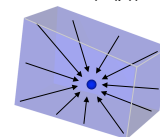


Ascending/Descending Manifolds

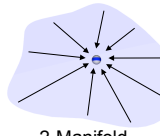
Descending Manifolds

$$D(p) = \{p\} \cup \{x \mid x \in I, \text{dest}(I) = p\}$$

$$\dim(D(p)) = \text{index}(p)$$



1-Manifold



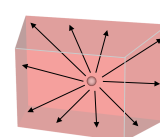
2-Manifold
● Maximum

0-Manifold
● 2-Saddle

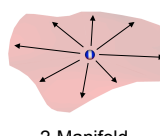
Ascending Manifolds

$$A(p) = \{p\} \cup \{x \mid x \in I, \text{orig}(I) = p\}$$

$$\dim(A(p)) = d - \text{index}(p)$$



1-Manifold

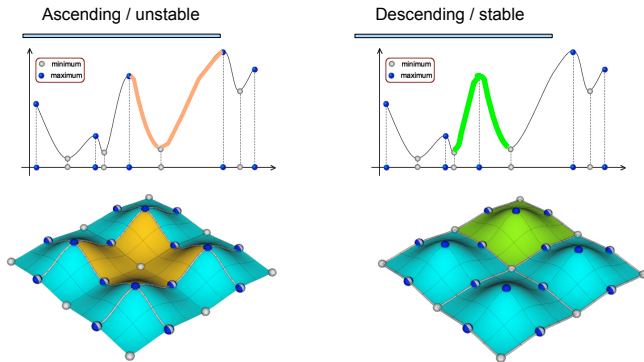


2-Manifold
● 1-Saddle

0-Manifold
● Minimum

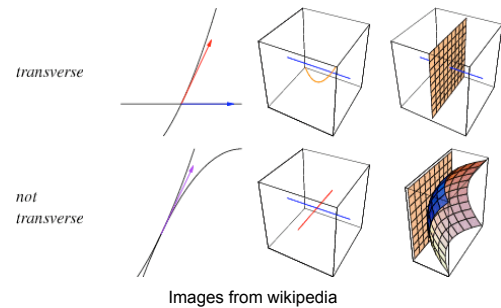
Morse Complex

- Ascending/Descending Morse Complex
 - Cell complex – partition of space



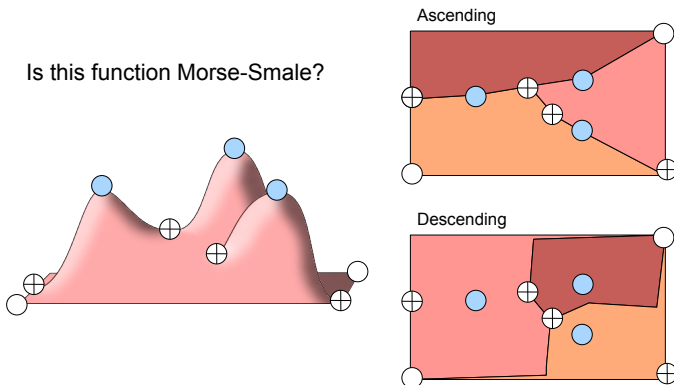
Morse-Smale function

- A *Morse-Smale function* is a Morse function where ascending and descending manifolds intersect only transversally



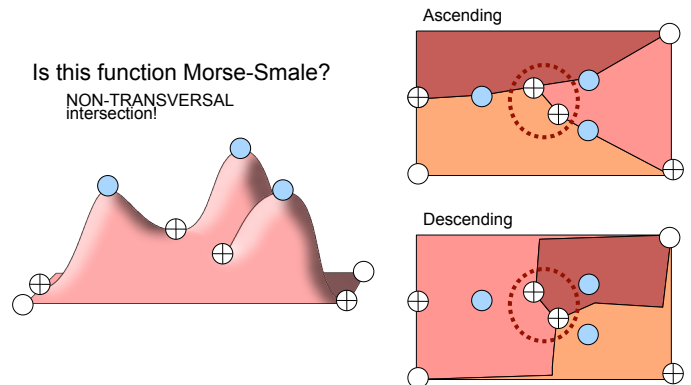
Morse Complex

Is this function Morse-Smale?



Morse Complex

Is this function Morse-Smale?
NON-TRANSVERSAL
intersection!



Morse-Smale function

- Transversal intersections:
 - Practically we say that
 - In 2d ascending/descending 1-manifolds cross at a point
 - In 3d ascending/descending 2-manifolds cross along arcs
- Can perturb a Morse function to make it Morse-Smale

Morse-Smale complex

- Given a Morse-Smale function
- The cell complex formed by the intersection of the ascending and descending manifolds is the *Morse-Smale complex*

Morse-Smale complex

1D domain

Morse-Smale complex

1D domain

Morse-Smale complex

1D domain

Arcs Nodes

Morse-Smale complex

2D domain

Morse-Smale complex

2D domain

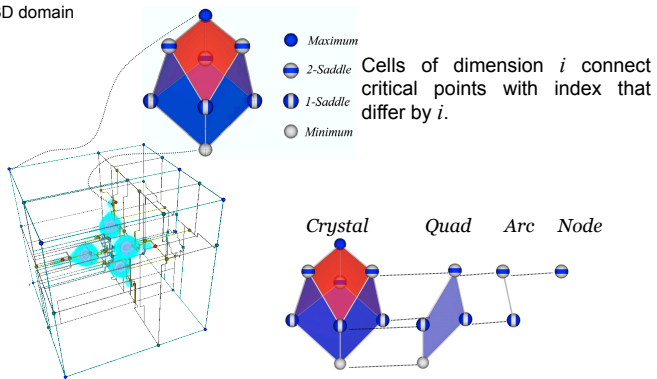
Morse-Smale complex

2D domain

Quad Arc Node

Morse-Smale complex

3D domain

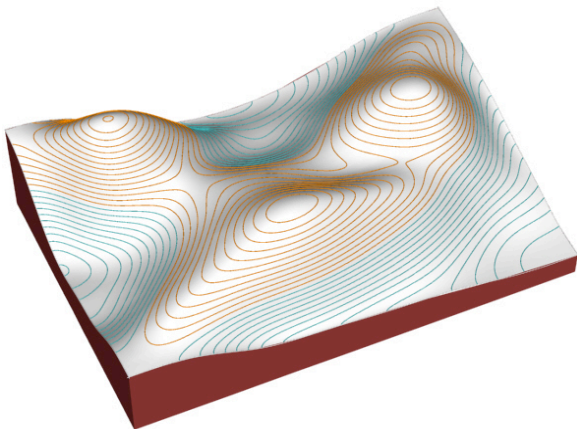


Morse-Smale complex

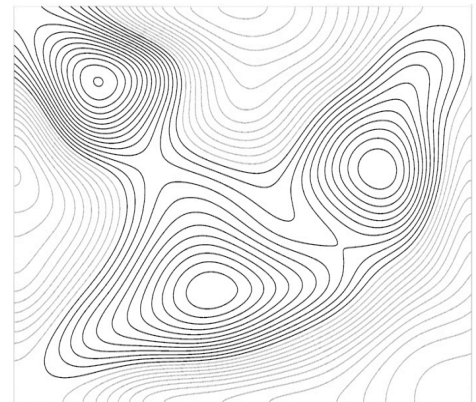
• Properties of cells

- What do contours look like?
- Can you extract the Morse complexes?
- Can you extract the Contour Trees?
- What is wrong with the definition:
 - A cell of the Morse-Smale complex is composed of the integral lines that share a common origin and destination?

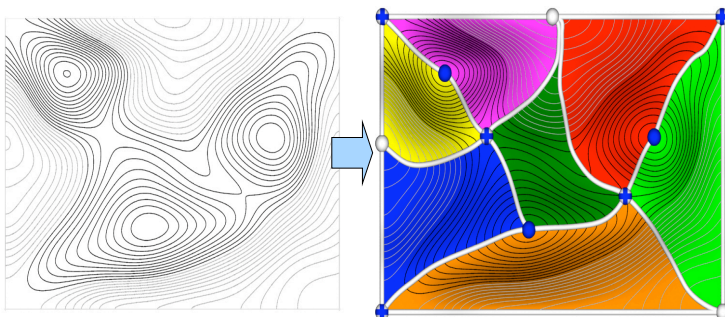
A Simple Example



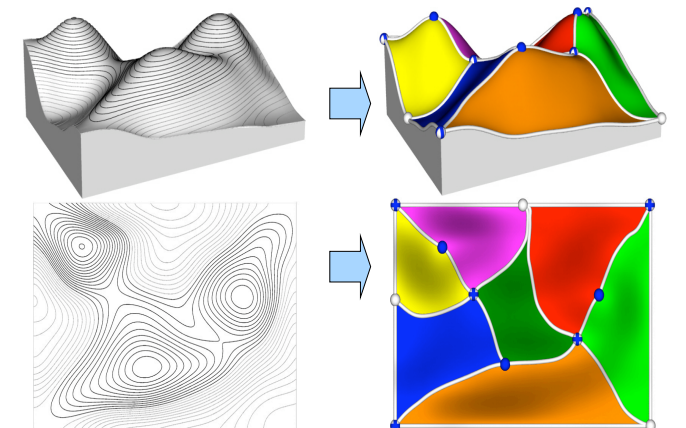
A Simple Example



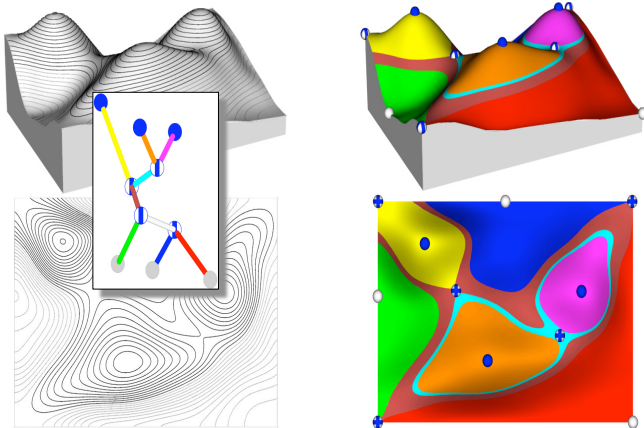
A Simple Example



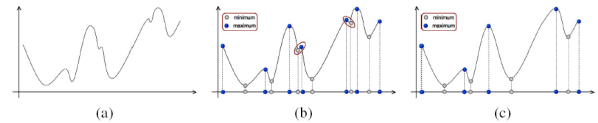
A Simple Example



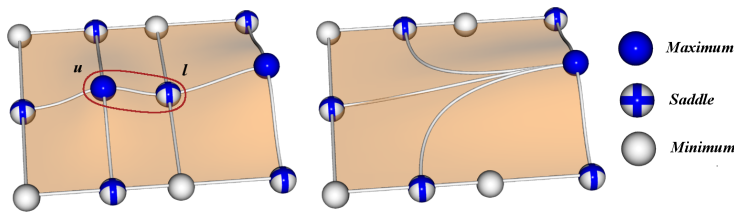
A Simple Example



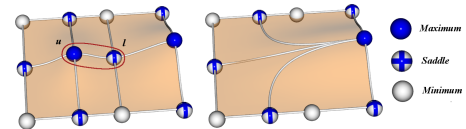
Simplification



Cancellations

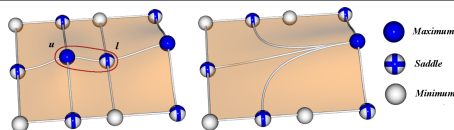


Cancellations – how does it look?



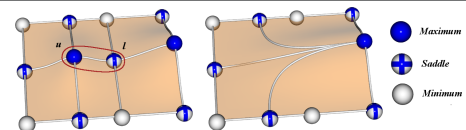
- What happens to the complex?
 - Cells are extended
 - Cells merge
 - Arcs merge
 - Arcs are deleted
 - Nodes are removed

Cancellations – a general definition



- Combinatorial change
 - Lower neighbors of the upper node are connected to upper neighbors of the lower node
 - All the arcs connected to u and l are removed
 - u and l are removed

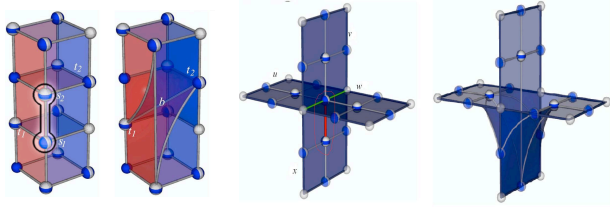
Cancellations – 2D case



- For the special case of 2D, a cancellation is the merging of an extremum-saddle-extremum

Cancellations – 3D case

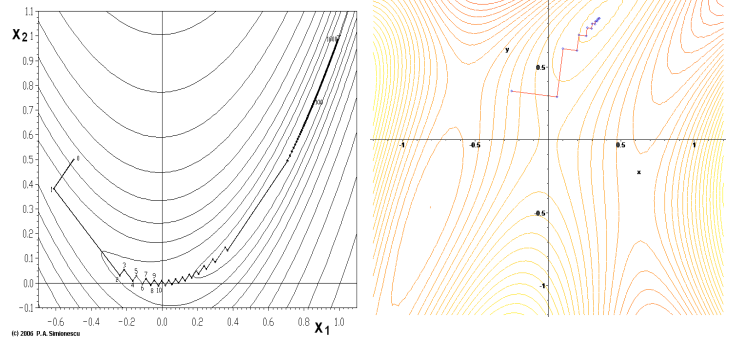
- Saddle-Extremum cancellations just as in 2D



- 1Saddle-2Saddle cancellations

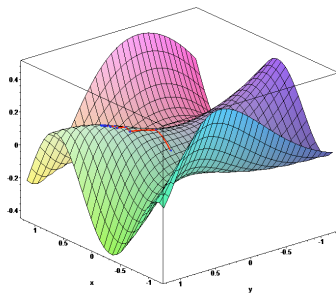
Computing the 2d MS complex

- Why don't we just integrate from every point?
 - Gradient descent



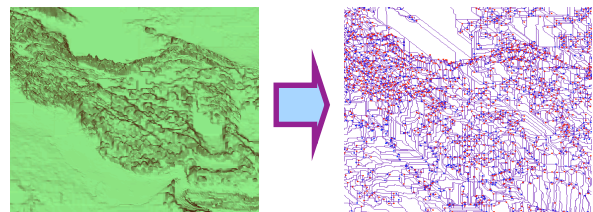
Computing the 2d MS complex

- Crossing integral lines!
 - Consistency – want quads
 - What do you do with degeneracies?
 - Flat regions
 - multi-saddles



Algorithm 1 – 2D MS complex

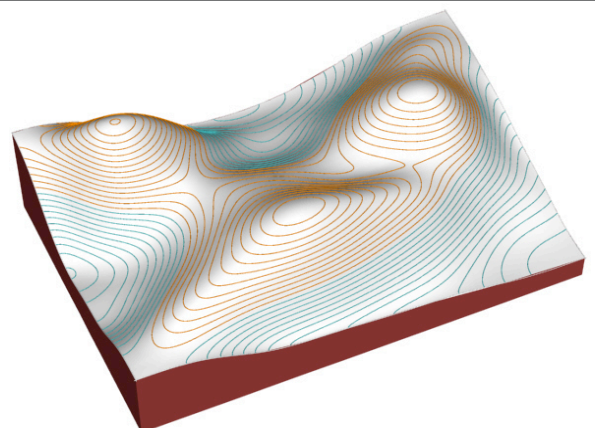
- Edelsbrunner et al. *Hierarchical Morse Complexes for Piecewise Linear 2-Manifolds*
 - Input: a scalar function on a simplicial 2-manifold mesh
 - Triangles, edges, vertices
 - Output: the Quasi-Morse-Smale complex



Algorithm 1 – 2D MS complex

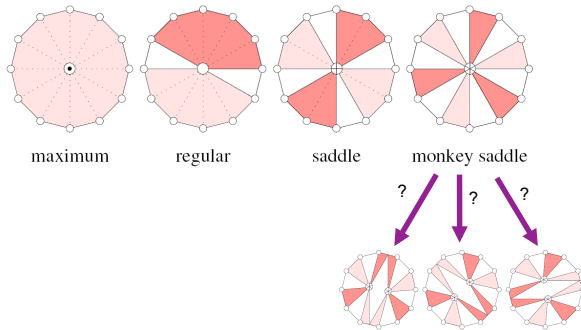
- 2-Stage Combinatorial algorithm
 - (0) identify all critical points
 - (1) trace descending paths from saddles
 - (2) trace ascending paths from saddles, not allowing crosses of descending lines

A Simple Example

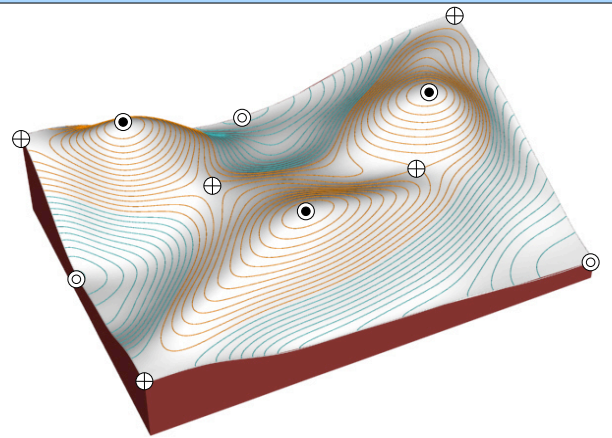


Algorithm 1 – 2D MS complex

- (0) identify all critical points

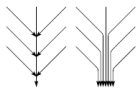
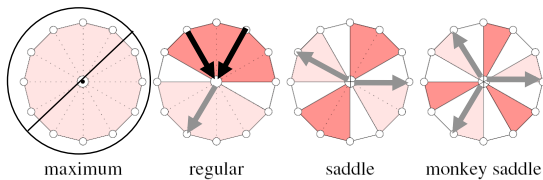


A Simple Example



Algorithm 1 – 2D MS complex

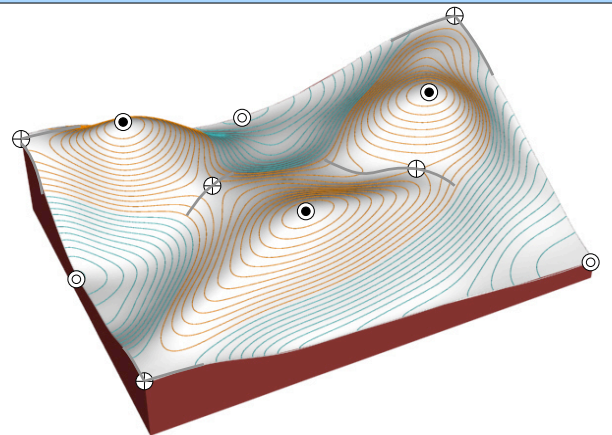
- (1) trace descending paths from saddles
 - Extend paths along steepest downward edge



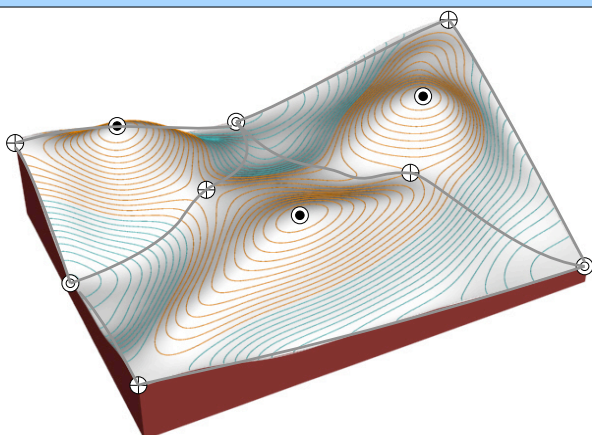
Merging paths are legal – represent a split between paths

ONCE THINGS MERGE THEY WILL NEVER SPLIT!!!!

A Simple Example

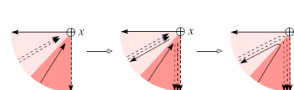
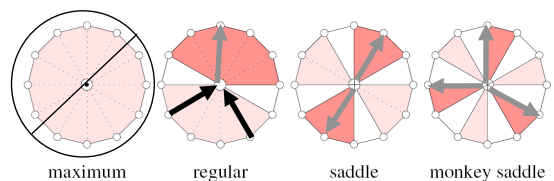


A Simple Example

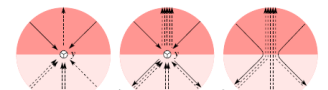


Algorithm 1 – 2D MS complex

- (2) trace ascending paths from saddles
 - Must be careful not to cross descending lines!!!!

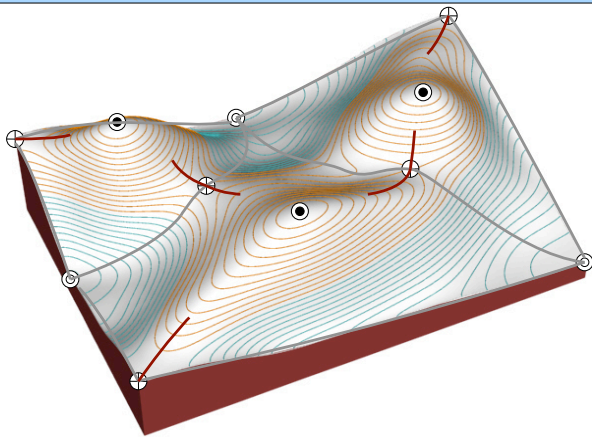


Paths ending at a saddle are forced around the saddle

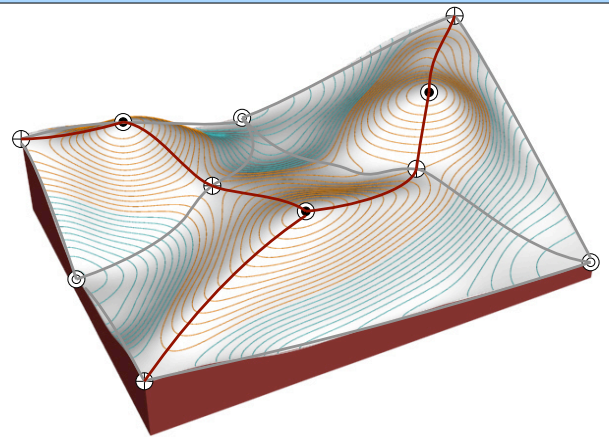


Ascending paths are forced not to intersect descending paths

A Simple Example

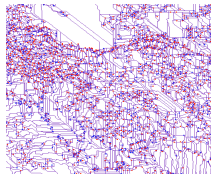
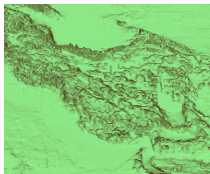
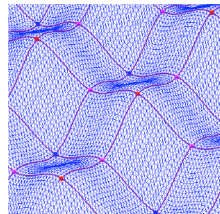


A Simple Example



Algorithm 1 – 2D MS complex

- Results
 - Combinatorial method
 - Handles degeneracies
 - Care has to be taken in keeping things separated



Algorithm 2 – 3D MS complex

- Why is simple extension of 2D ideas difficult?
 - Trace descending manifolds
 - Arcs and surfaces from saddles
 - Trace ascending manifolds, keeping them separate from existing descending manifolds

H. Edelsbrunner, J. Harer, V. Natarajan and V. Pascucci. Morse-Smale complexes for piecewise linear 3-manifolds. In "Proc. 19th Ann. Sympos. Comput. Geom. 2003", 361-370.

Algorithm 3 – Discrete MS complex

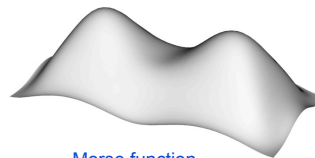
- Simple, generic, applicable to any dimension
- Based on discrete Morse theory:

R. Forman. *A users guide to discrete Morse theory*. In Proc. of the 2001 Internat. Conf. on Formal Power Series and Algebraic Combinatorics, A special volume of Advances in Applied Mathematics, page 48, 2001.

T. Lewiner. *Constructing discrete Morse functions*. Master's thesis, Department of Mathematics, PUC-Rio, 2002.

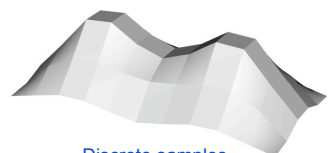
Continuous to discrete Morse theory

Continuous Case



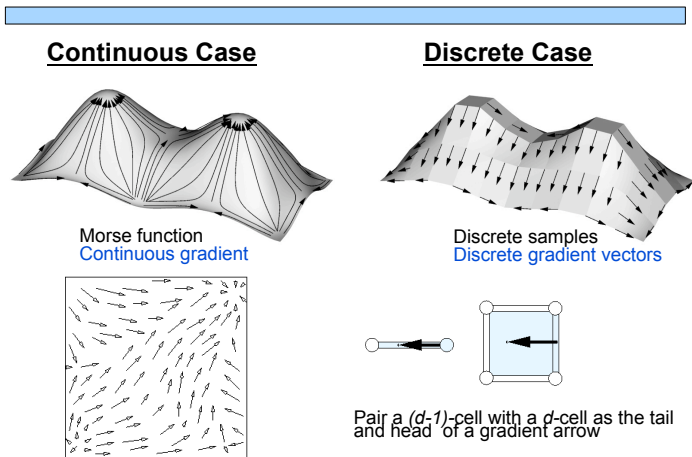
Morse function

Discrete Case

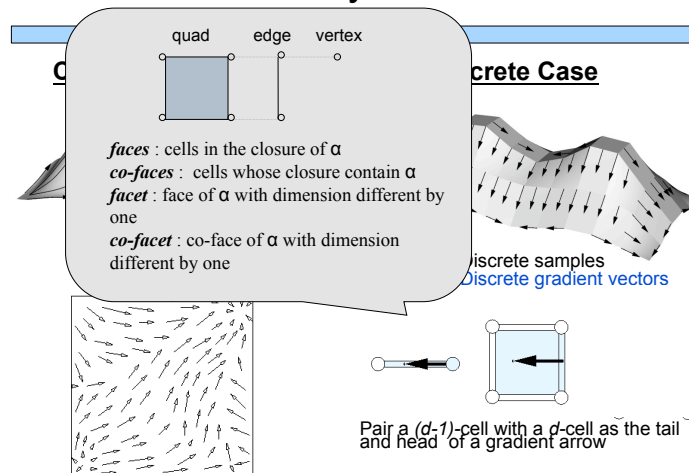


Discrete samples

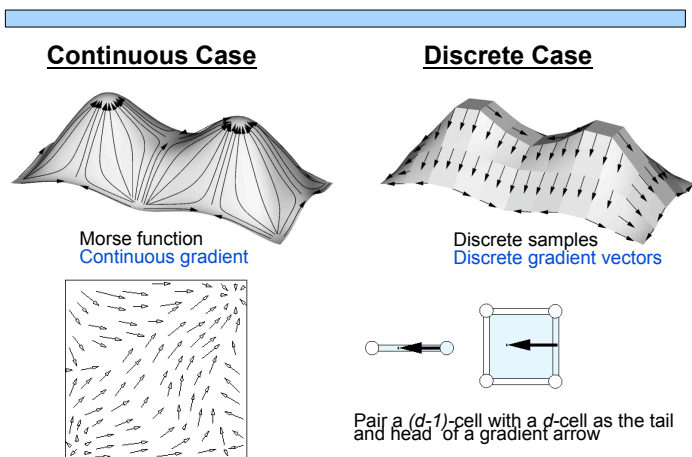
Continuous to discrete Morse theory



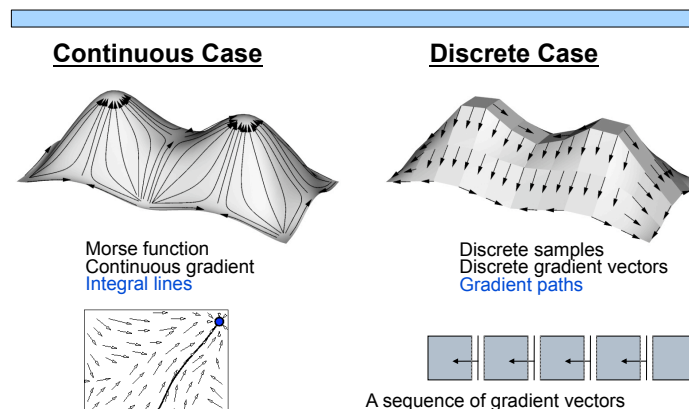
Continuous to discrete Morse theory



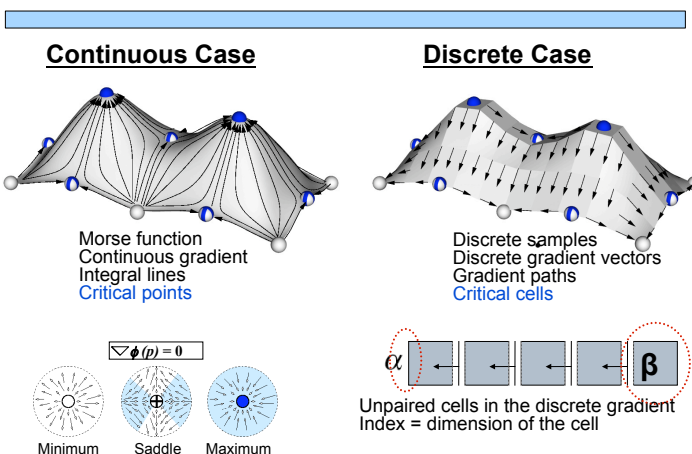
Continuous to discrete Morse theory



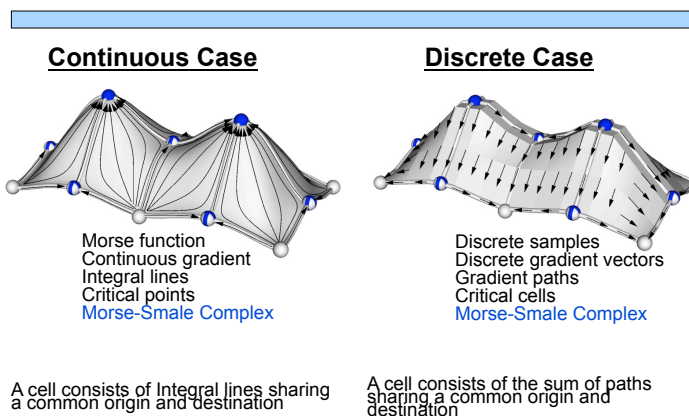
Continuous to discrete Morse theory



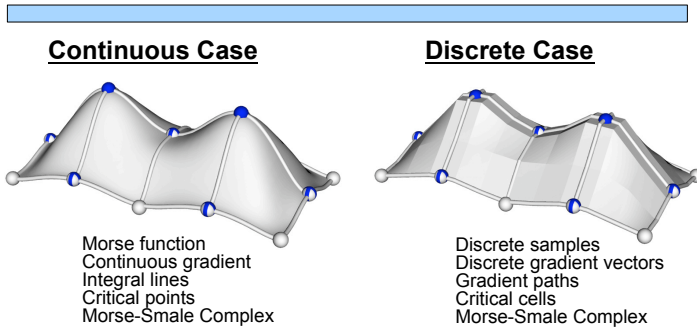
Continuous to discrete Morse theory



Continuous to discrete Morse theory



Continuous to discrete Morse theory

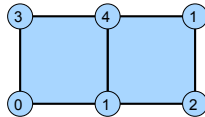


Algorithm 3 – Discrete MS complex

- Construct a discrete gradient vector field
- Trace ascending and descending manifolds

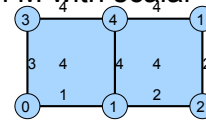
Computing the discrete gradient on a mesh

- Given a mesh M with scalar valued defined at vertices



Computing the discrete gradient on a mesh

- Given a mesh M with scalar valued defined at vertices

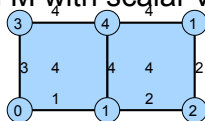


- Assign a value to every cell

$$F(\alpha) = \text{MAX}\{\sigma : \sigma < \alpha\} + \varepsilon$$

Computing the discrete gradient on a mesh

- Given a mesh M with scalar valued defined at vertices



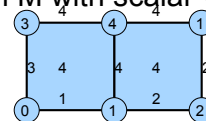
- Create gradient arrows in direction of steepest descent

```

For i = 0, ..., d
  While not all i-cells have been marked
    lowest = Lowest_Unmarked_iCell()
    If Can_Pair (lowest)
      Pair_With_Steepest_Descent_cofacet(lowest)
    Else
      Set_Critical(lowest)
  
```

Computing the discrete gradient on a mesh

- Given a mesh M with scalar valued defined at vertices



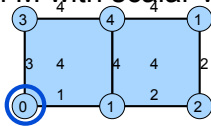
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Computing the discrete gradient on a mesh

- Given a mesh M with scalar valued defined at vertices



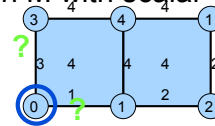
- Create gradient arrows in direction of steepest descent

```

For  $i = 0, \dots, d$   $i = 0$ 
  While not all  $i$ -cells have been marked
     $lowest = \text{Lowest\_Unmarked\_iCell}()$ 
    If  $\text{Can\_Pair}(lowest)$ 
      Pair_With_Steepest_Descent_cofacet( $lowest$ )
    Else
      Set_Critical( $lowest$ )
  
```

Computing the discrete gradient on a mesh

- Given a mesh M with scalar valued defined at vertices



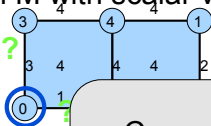
- Create gradient arrows in direction of steepest descent

```

For  $i = 0, \dots, d$   $i = 0$ 
  While not all  $i$ -cells have been marked
     $lowest = \text{Lowest\_Unmarked\_iCell}()$ 
    If  $\text{Can\_Pair}(lowest)$ 
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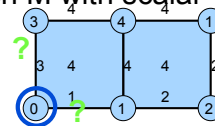
```

For  $i = 0, \dots, d$   $i = 0$ 
  While not all  $i$ -cells have been marked
     $lowest = \text{Lowest\_Unmarked\_iCell}()$ 
    If  $\text{Can\_Pair}(lowest)$ 
      Pair_With_Steepest_Descent_cofacet( $lowest$ )
    Else
      Set_Critical( $lowest$ )
  
```

Can pair α with β if α is only unmarked facet of β and $f(\alpha) < f(\beta)$

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- Given a mesh M with scalar valued defined at vertices



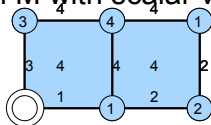
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  While not all  $i$ -cells have been marked
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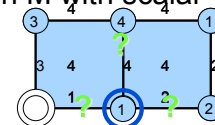
```

For  $i = 0, \dots, d$   $i = 0$ 
  While not all  $i$ -cells have been marked
     $lowest = \text{Lowest\_Unmarked\_iCell}()$ 
    If  $\text{Can\_Pair}(lowest)$ 
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- Given a mesh M with scalar valued defined at vertices



- Create gradient arrows in direction of steepest descent

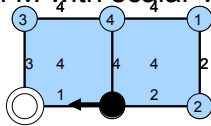
```

For  $i = 0, \dots, d$   $i = 0$ 
  While not all  $i$ -cells have been marked
     $lowest = \text{Lowest\_Unmarked\_iCell}()$ 
    If  $\text{Can\_Pair}(lowest)$ 
      Pair_With_Steepest_Descent_cofacet( $lowest$ )
    Else
      Set_Critical( $lowest$ )
  
```



Computing the discrete gradient on a mesh

- Given a mesh M with scalar valued defined at vertices



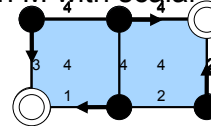
- Create gradient arrows in direction of steepest descent

```

For  $i = 0, \dots, d$   $i = 0$ 
  While not all  $i$ -cells have been marked
     $lowest = \text{Lowest\_Unmarked\_iCell}()$ 
    If  $\text{Can\_Pair}(lowest)$ 
      →  $\text{Pair\_With\_Steepest\_Descent\_cofacet}(lowest)$ 
    Else
       $\text{Set\_Critical}(lowest)$ 
  
```

Computing the discrete gradient on a mesh

- Given a mesh M with scalar valued defined at vertices



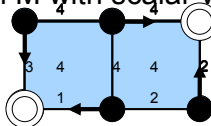
- Create gradient arrows in direction of steepest descent

```

For  $i = 0, \dots, d$   $i = 0$ 
  While not all  $i$ -cells have been marked
     $lowest = \text{Lowest\_Unmarked\_iCell}()$ 
    If  $\text{Can\_Pair}(lowest)$ 
      →  $\text{Pair\_With\_Steepest\_Descent\_cofacet}(lowest)$ 
    Else
       $\text{Set\_Critical}(lowest)$ 
  
```

Computing the discrete gradient on a mesh

- Given a mesh M with scalar valued defined at vertices



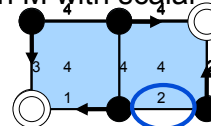
- Create gradient arrows in direction of steepest descent

```

For  $i = 0, \dots, d$   $i = 1$ 
  While not all  $i$ -cells have been marked
     $lowest = \text{Lowest\_Unmarked\_iCell}()$ 
    If  $\text{Can\_Pair}(lowest)$ 
       $\text{Pair\_With\_Steepest\_Descent\_cofacet}(lowest)$ 
    Else
       $\text{Set\_Critical}(lowest)$ 
  
```

Computing the discrete gradient on a mesh

- Given a mesh M with scalar valued defined at vertices



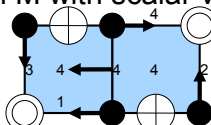
- Create gradient arrows in direction of steepest descent

```

For  $i = 0, \dots, d$   $i = 1$ 
  While not all  $i$ -cells have been marked
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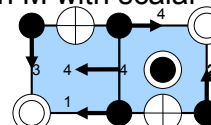
- Create gradient arrows in direction of steepest descent

```

For  $i = 0, \dots, d$   $i = 1$ 
  While not all  $i$ -cells have been marked
     $lowest = \text{Lowest\_Unmarked\_iCell}()$ 
    If  $\text{Can\_Pair}(lowest)$ 
       $\text{Pair\_With\_Steepest\_Descent\_cofacet}(lowest)$ 
    Else
       $\text{Set\_Critical}(lowest)$ 
  
```

Computing the discrete gradient on a mesh

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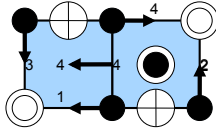
- Create gradient arrows in direction of steepest descent

```

For  $i = 0, \dots, d$   $i = 2$ 
  While not all  $i$ -cells have been marked
     $lowest = \text{Lowest\_Unmarked\_iCell}()$ 
    If  $\text{Can\_Pair}(lowest)$ 
       $\text{Pair\_With\_Steepest\_Descent\_cofacet}(lowest)$ 
    Else
       $\text{Set\_Critical}(lowest)$ 
  
```


Computing the discrete gradient on a mesh

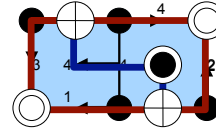
- Now we have a discrete gradient!



- The Morse-Smale complex is given by simply tracing gradient paths
 - Arcs are paths that start and end at critical cells

Computing the discrete gradient on a mesh

- Now we have a discrete gradient!



- The Morse-Smale complex is given by simply tracing gradient paths
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References

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Questions?